

## AE 6511 OPTIMAL GUIDANCE AND CONTROL

**Catalog Data:** AE 6511. Optimal Guidance and Control 3-0-3. Prerequisite: AE 3501 or equivalent. Euler-Lagrange formulation; Hamilton-Jacobi approach; Pontryagin's minimum principle; Systems with quadratic performance index; Second variation and neighboring extremals; Singular solutions; Numerical solution techniques.

**Coordinator:** J.V.R. Prasad, Associate Professor

**Textbook:**

Bryson, Arthur E., Jr., and Ho, Yu-Chi: Applied Optimal Control, John Wiley & Sons, New York, 1975.

**Educational Objectives:** This course offers students a basic knowledge in optimal control theory and its applications in the area of optimal guidance and control of aerospace systems.

<u>Topics</u>	<u>Hours</u>
1. Introduction	1
2. Parameter Optimization Problems	2
3. Optimization problems for dynamic systems	4
4. Optimization problems for dynamic systems with path constraints	5
5. Dynamic programming	4
6. Linear systems with quadratic criteria	4
7. Time, fuel and energy optimal systems	5
8. Second variation and neighboring extremals	5
9. Singular solutions	3
10. Standard computational methods	7
Quizzes and Instructor's option	5
Total	<hr/> 45

**Computer Usage:**

Individual student projects involve computer program development for numerical solution to optimal control problems.

**Laboratory Projects:**

None